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machine. The theoretical principles involved in machines have immediate application to practical problems. Designed as a text for the undergraduate students of mechanical engineering, it covers all the basics of mechanism and machine theory in a simple and logical manner. The basic theory presented in the book has been evolved out of simple and readily understood principles. The text begins with the discussion on various types of mechanisms and their working principles. Further it discusses the working of Oldham's coupling, automobiles steering gears, engine pressure indicators, and estimation of velocity and acceleration using relative velocity method, complex

algebra method and instantaneous centre method. Types of friction and power transmission by belt drives are also explained in detail. Finally it concludes with cam and follower mechanism. KEY FEATURES : Balanced presentation of the graphical and algebraic approaches Numerous solved and unsolved problems in each chapter Wide coverage of topics as per the latest syllabi of various universities

The second edition of Shigley-Uicker maintains the tradition of being very complete, thorough, and somewhat theoretical. The principal changes include an expansion and updating of the dynamics material, expansion of

the chapter on gears, an expansion of the material on mechanisms, a new introductory chapter. Intended for the Kinematics and Dynamics course in Mechanical Engineering departments.

This work is a supplement to accompany the authors' main text. It contains solutions to the problems in the book and is available free of charge to adopters.

Theory of Machines and Mechanisms, Third Edition, is a comprehensive study of rigid-body mechanical systems and provides background for
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continued study in stress, strength, fatigue, life, modes of failure, lubrication and other advanced aspects of the design of mechanical systems. This third edition provides the background, notation, and nomenclature essential for students to understand the various and independent technical approaches that exist in the field of mechanisms, kinematics, and dynamics of machines. The authors employ all methods of analysis and development, with balanced use of graphical and analytic methods. New material includes an introduction of kinematic coefficients, which clearly separates kinematic (geometric) effects from speed or dynamic dependence. At the

suggestion of users, the authors have included no written computer programs, allowing professors and students to write their own and ensuring that the book does not become obsolete as computers and programming languages change. Part I introduces theory, nomenclature, notation, and methods of analysis. It describes all aspects of a mechanism (its nature, function, classification, and limitations) and covers kinematic analyses (position, velocity, and acceleration). Part II shows the engineering applications involved in the selection, specification, design, and sizing of mechanisms that accomplish specific motion objectives. It includes chapters on cam systems, gears, gear trains,

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